



Autonomous Operational Scheduling on CogniSat-6 Based on Onboard Artificial Intelligence

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Introduction

Ubotica's Purpose

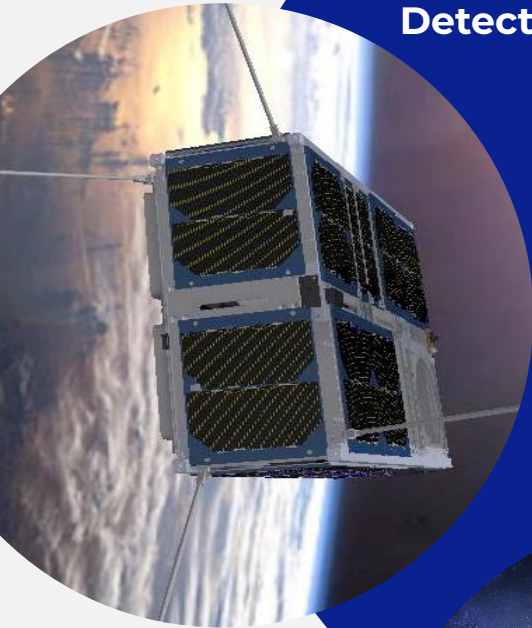
To disrupt the Satellite Services Market by transforming satellites into smart, autonomous, collaborative robots that generate persistent, real-time, insights of high value



Our Space Flight Heritage

PhiSat-1

launched September 2020
Detecting clouds in EO data in
real-time
First ever On-Satellite
Hardware Accelerated
AI Inference



ISS

launched March 2021
**Landmark detection,
Flood Detection**



D-Orbit ION Wild Ride

launched June 2021
Cloud Computing on satellite
The world's first space mission
using radiation-tolerant
advanced heterogeneous
computing technologies

Ship detection demonstration



Why AI on board matters - the EO story

Problems:

1. EO spacecraft collect significant amounts of non-valuable data
2. System resources are limited (storage, downlink, power)
3. EO spacecraft typically operate in “mow-the-lawn” fashion

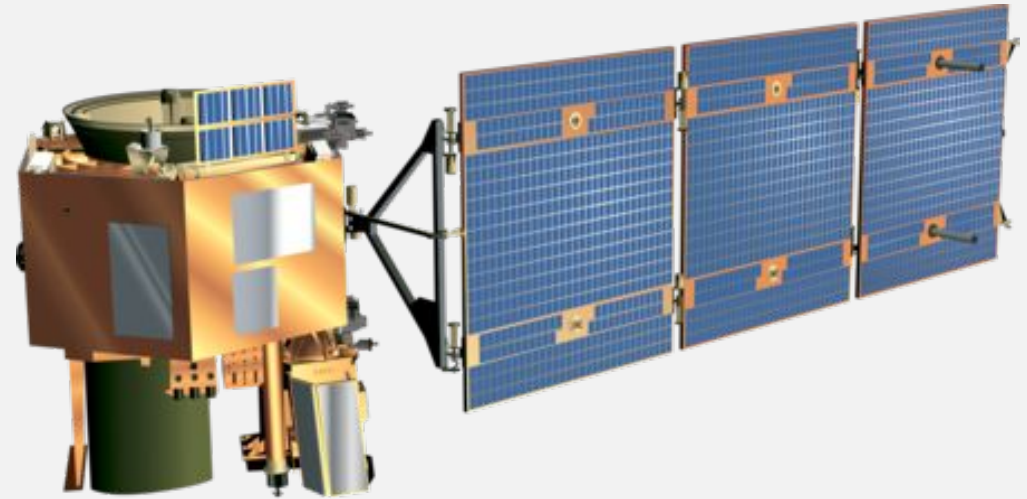
Solutions:

1. Non valuable data can be identified
2. System resources can be used more efficiently by prioritising valuable information or discarding non-valuable data
3. EO spacecraft can operate dynamically by interpreting context

A Non-Exhaustive Overview of Autonomous Scheduling Up To Now

EO-1

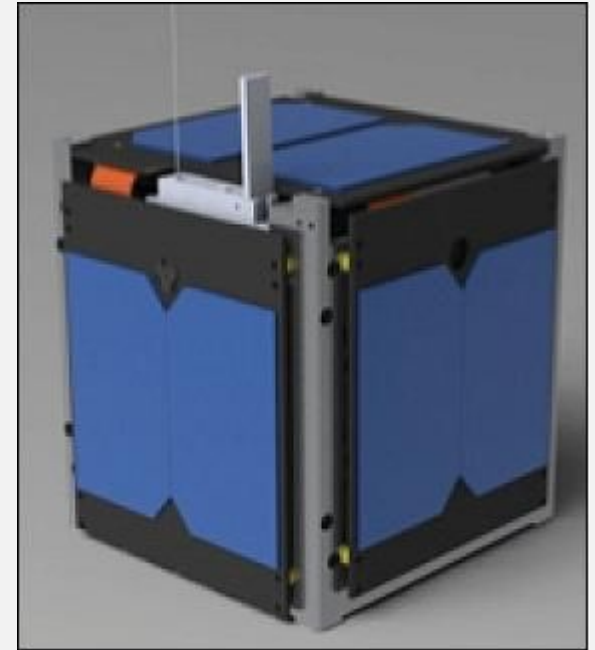
- Operational from 2004-2017
- Extracted events that are of the highest science value using decision trees and SVM's.
- Autonomous onboard planning
- 550+ kg



NASA, Public domain, via Wikimedia Commons

IPEX (Intelligent Payload Experiment)

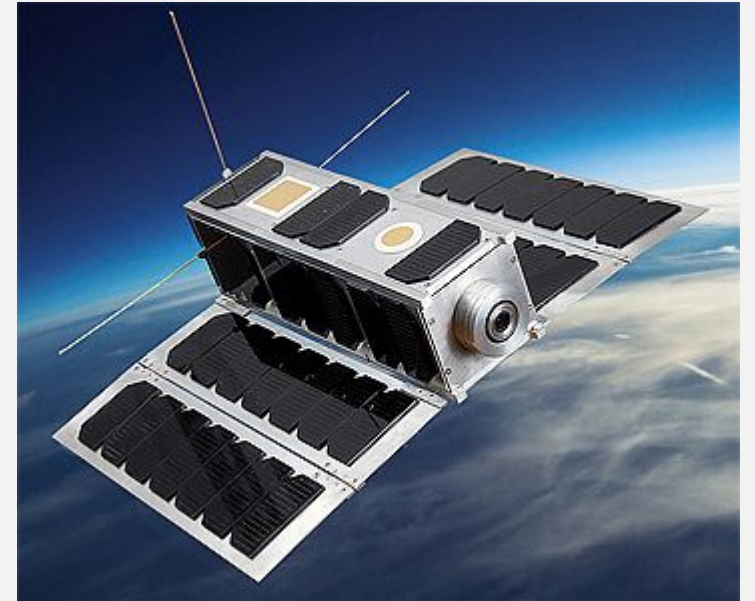
- Operational from 2013-2015
- Machine learning methods, SVM, spectral unmixing techniques, TextureCam random forest classifier, and image salience analysis
- Onboard scheduling of follow-on acquisitions
- 1U CubeSat



NASA

OPS-SAT

- Operational from 2019-now
- First demonstration of onboard training of AI models
- Installation of “apps” via NMF
- AI-in-the-loop EO
- Autonomous planner tested on ground
- 3U CubeSat



ESA

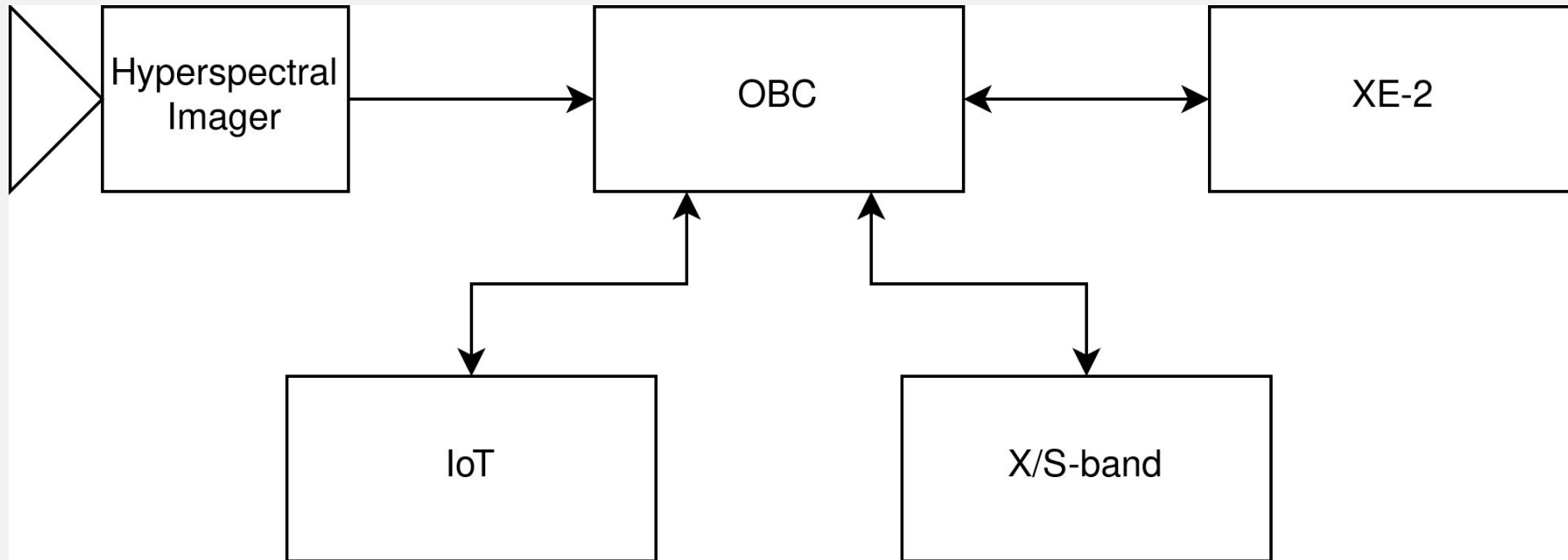
CogniSat-6

- Joint mission Ubotica and Open Cosmos
- Operational from Q1 2024
- High resolution hyperspectral sensor
- Onboard AI accelerator
- Inter-satellite communication
- 6U CubeSat



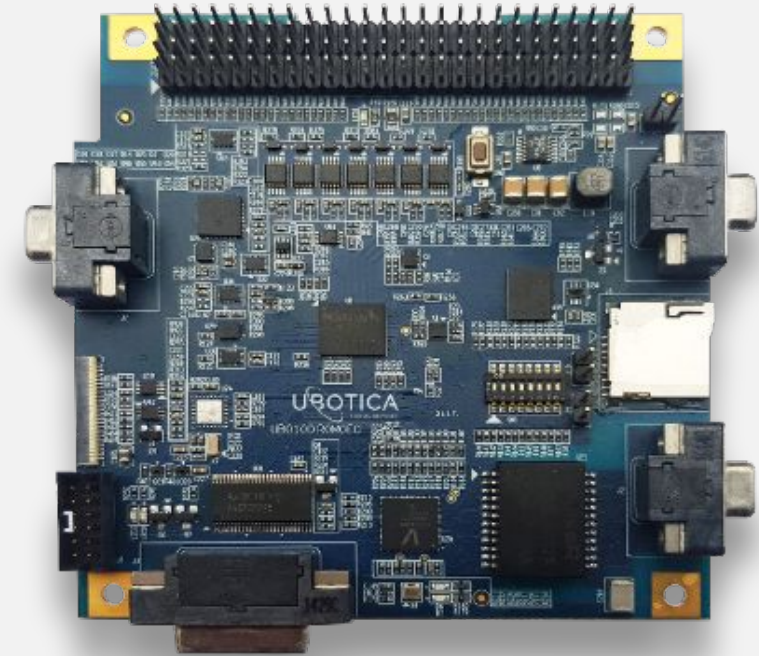
System Overview

CogniSat-6 System Overview



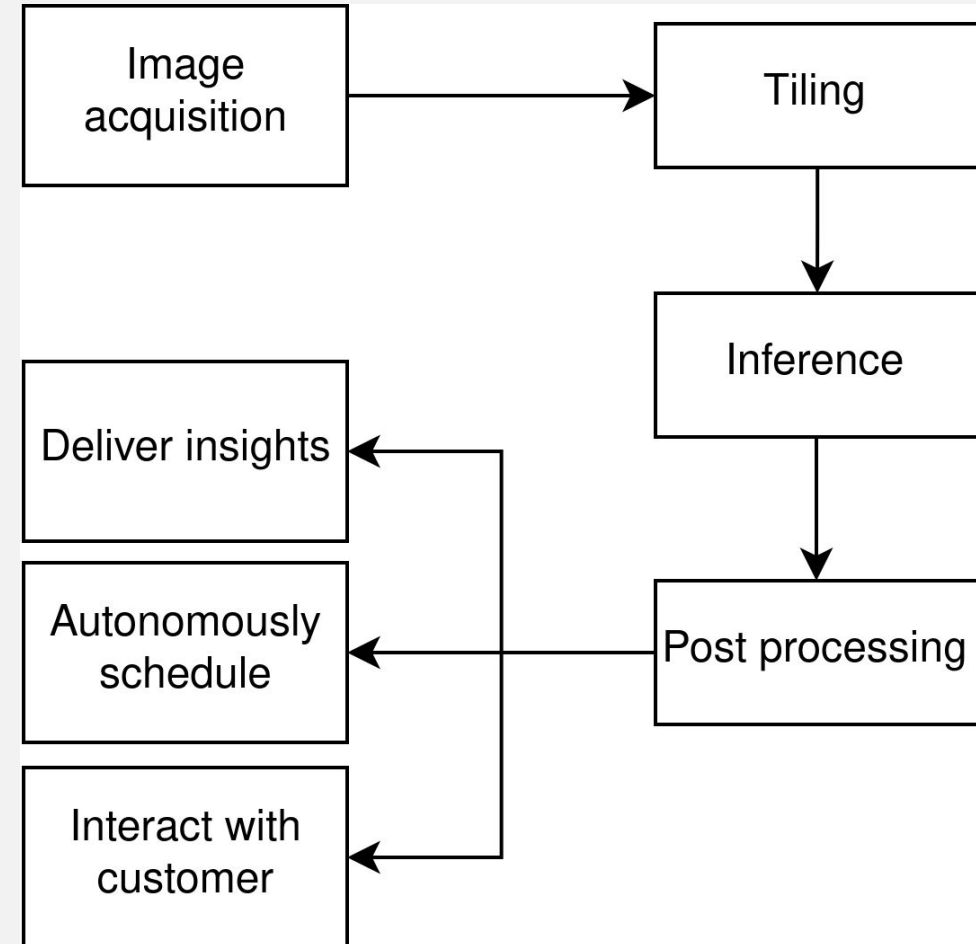
CogniSat-XE2 Processing Platform

- 1 TOPS NN compute
- 4 TOPS Imaging/Vision acceleration
- Low power: 1.5-3.5W when inferencing
- Latch-up protection on all internals
- Radiation tested
- Small (0.2U) and light (55.9 grams)



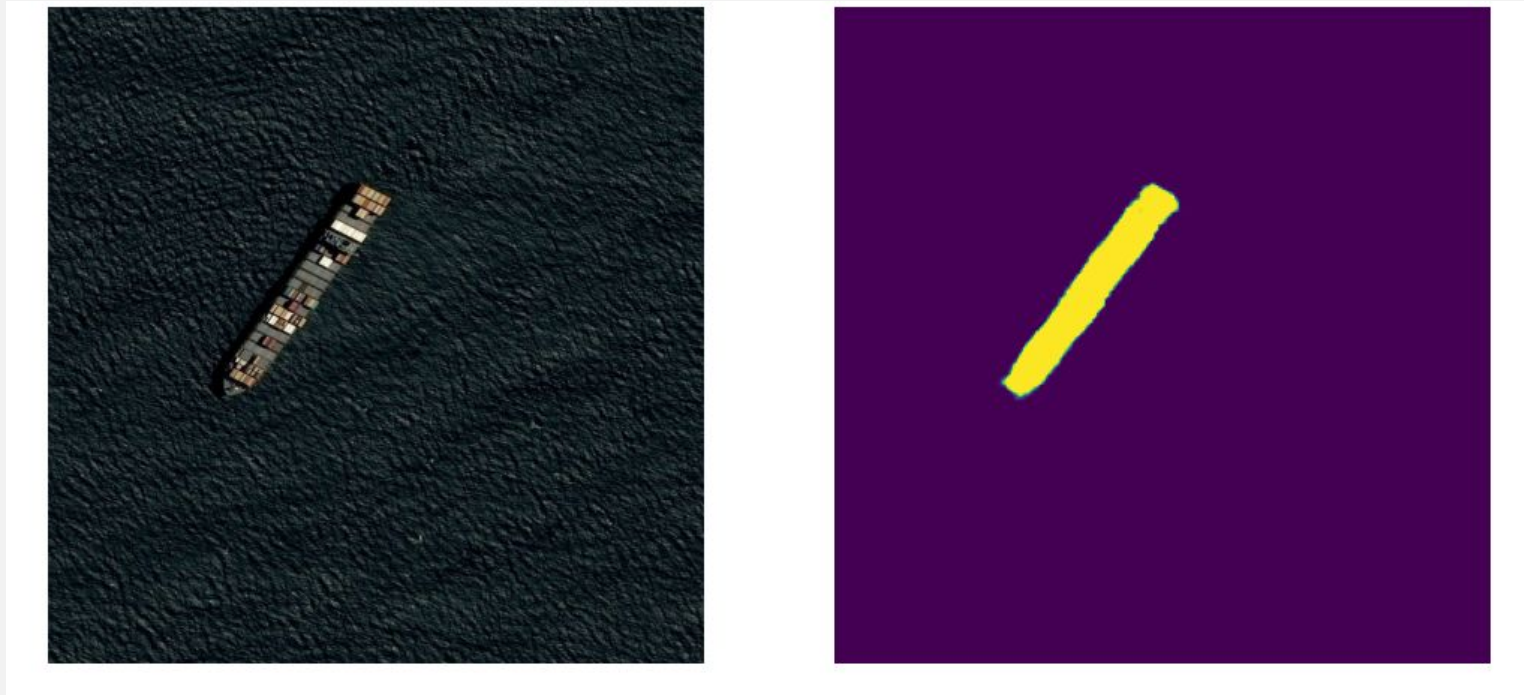
Processing Data

- End-to-end delivery of information extracted from 20x20 km image within 5 minutes from acquisition to end user on ground
- Neural Networks can be dynamically selected



Ship Segmentation

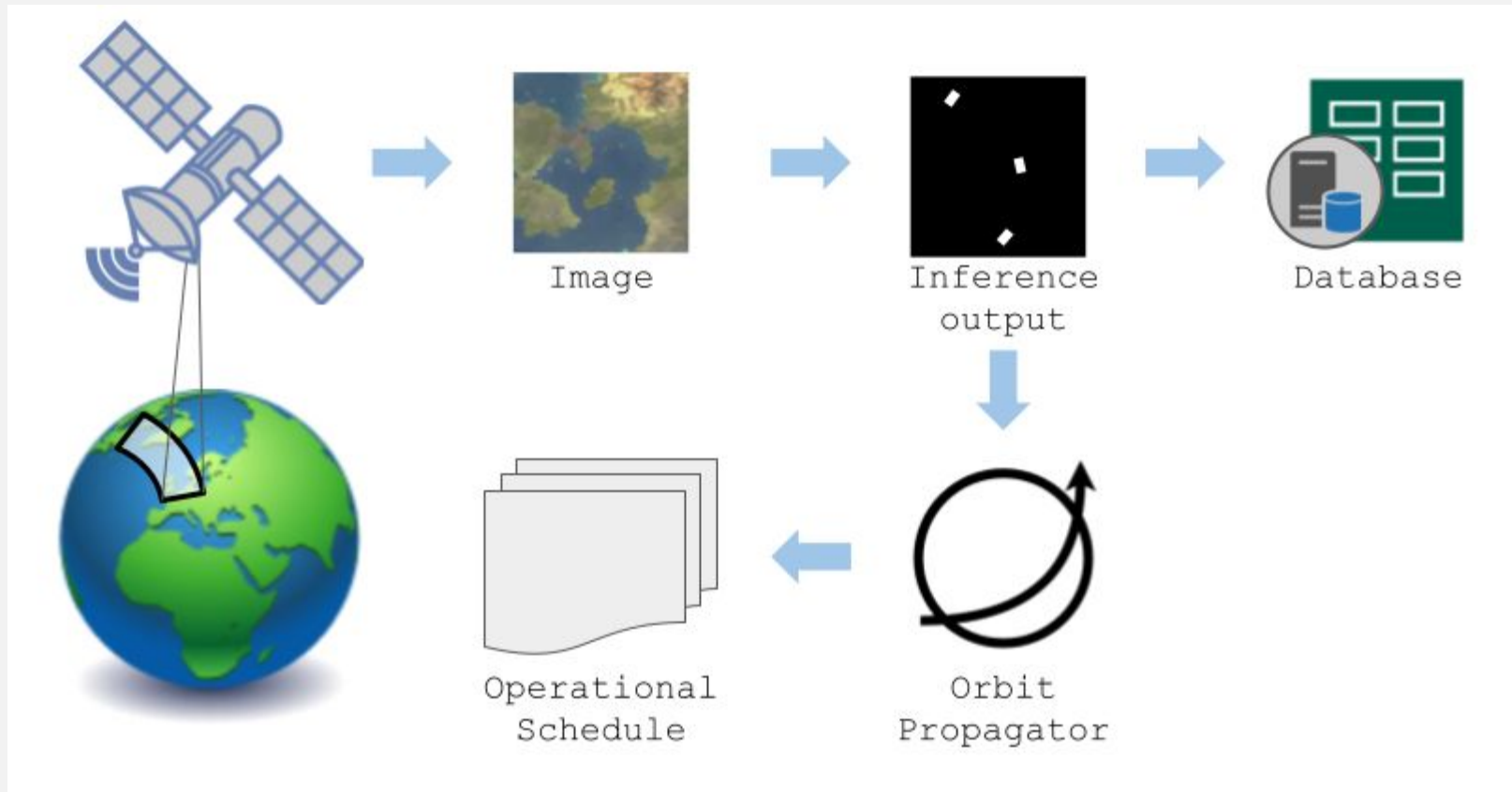
CogniSat-6 will perform inference on raw EO data



inversion, Jeff Faudi, Martin. (2018). Airbus Ship Detection Challenge. Kaggle.
<https://kaggle.com/competitions/airbus-ship-detection>

Autonomous Scheduling

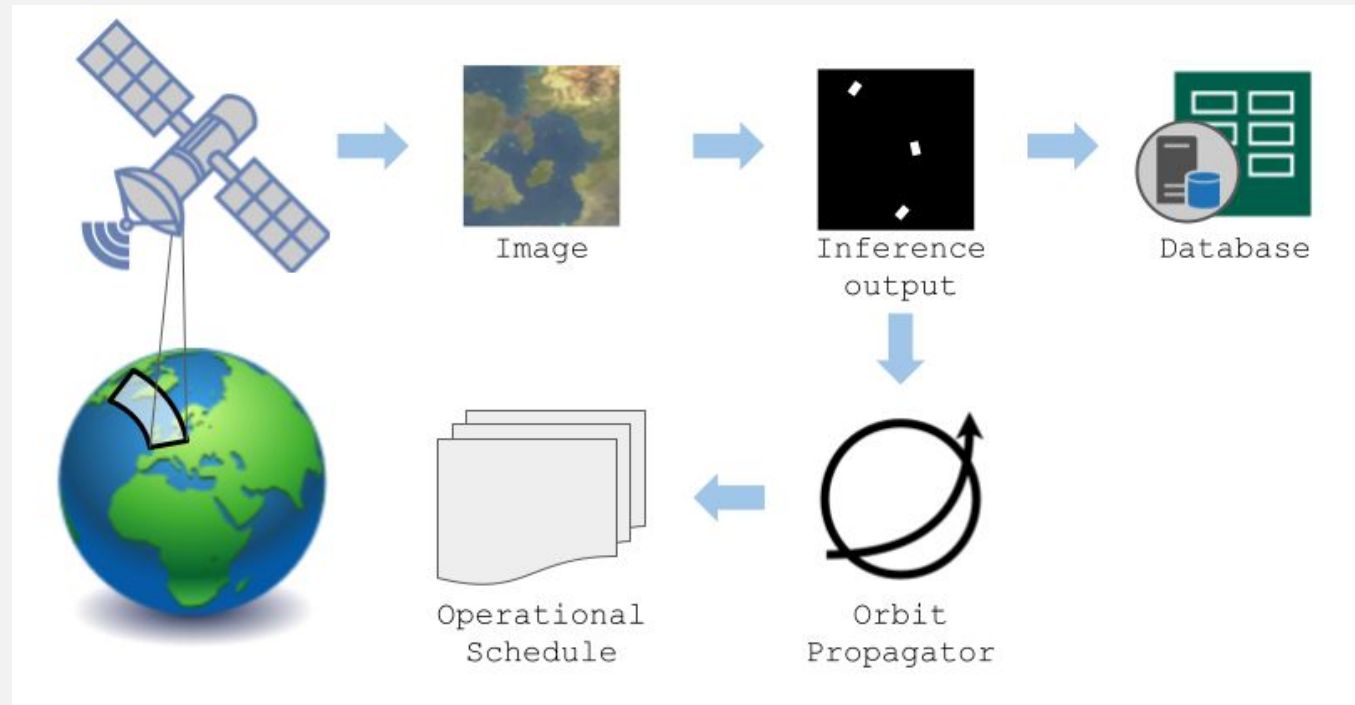
Autonomous Scheduling



All processed depicted here run on spacecraft

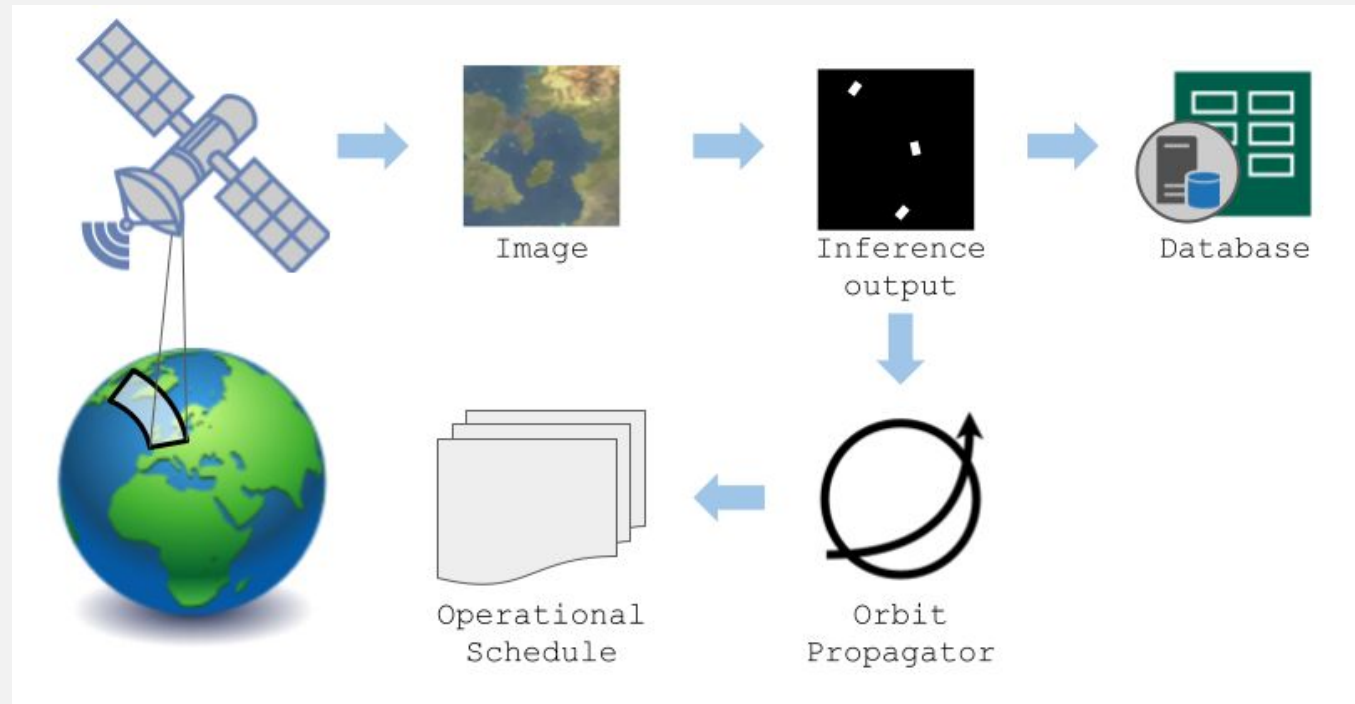
Autonomous Scheduling

- No ground station in the loop
 - Optionally, ground can be informed over ISL
- Ability to share locations of interest with other systems over ISL
- Runs on CubeSat hardware in real time



Benefits of Autonomous Scheduling

- Guarantees value of next acquisition for end-user
- Reduces system response time to events
- Enables tip and cue scenarios for constellations
- Enables complex system responses based on context:
 - “If a forest fire is detected AND human activity is spotted within 500 meters from this event, reschedule acquisition”

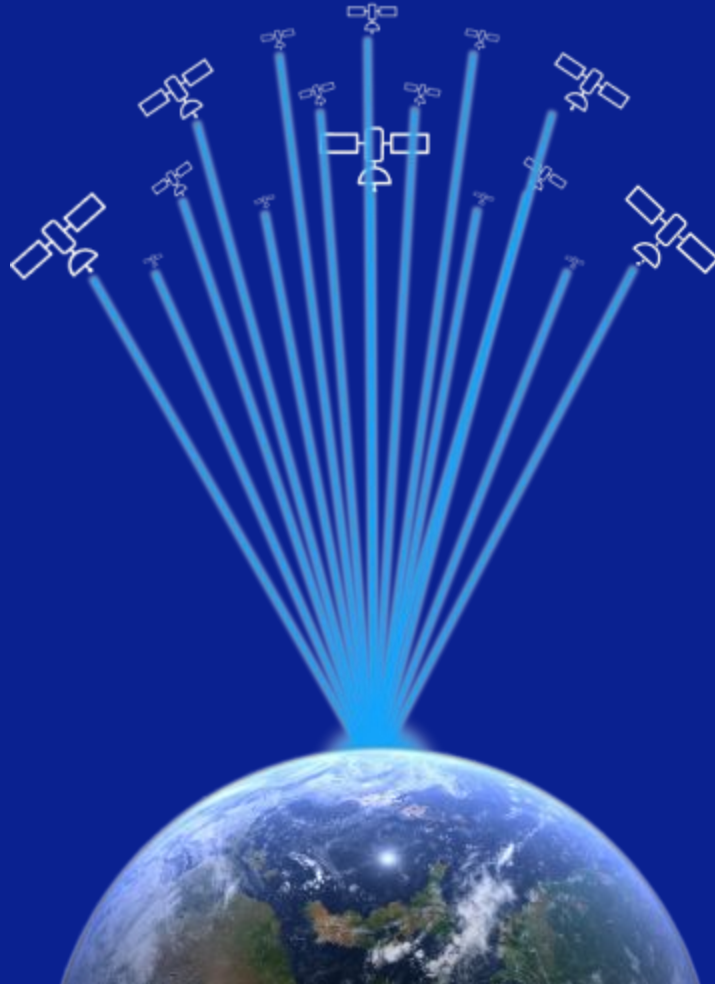


Conclusion

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- Onboard AI increases value generation by EO systems by order of magnitude
- Future work will present other CONOPs and operational results

OLD
Centralised
Intelligence
Simple satellites



NEW
Edge
Intelligence
Smart satellites



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